

The inside of the robot looks like a face. The color sensors are the eyes and the wheels are—very big— ears then the blask stabilizer is the mouth. Ok now let's get to what the real thing is made of, the two motors that move the wheels





# Why is it a box?

- 1. It makes space to connect attachments
- 2. The structure makes it more stable, and reduces the center of gravity
- 3.It keeps it dark for the color sensor able to focus better

Basically it helps with task.

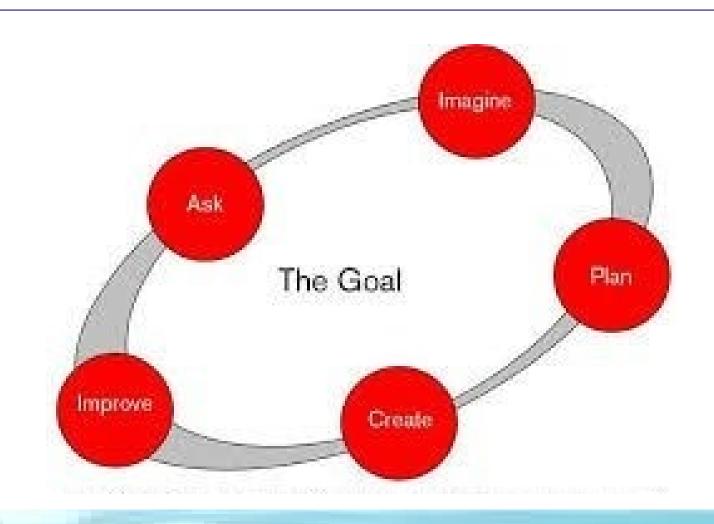


## Design Iteration

We had many ideas that developed into our attachments today. One main idea was our attachment for the windmill.

We had the idea by research, and trial/error

We had the design, but overall it was very complicated. So due to trial and error we made the useful design today.



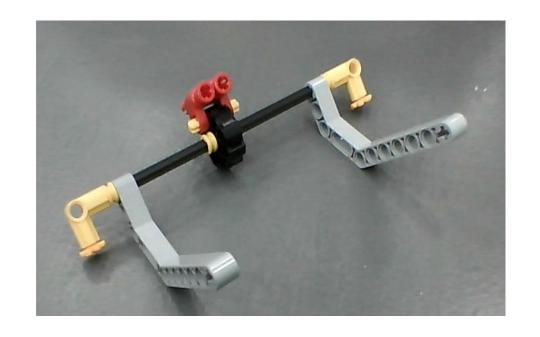
## PROGRAMING

For the first competition we had all singular codes, but we had to improve the codes for the state competition. We have two complete chain codes saved on our robot, named Eagle. We used multiple types of code blocks to make our robot move side to side and back and forth. The coding that we used made the robot run smoothly across the field. We chose not use any sensors in our codes because our codes were already perfected without them. We mostly used the pink movement code blocks, and the blue motor code blocks.

### Attachments

The Dino Dragger

Used to move energy to middle and dino to other side.

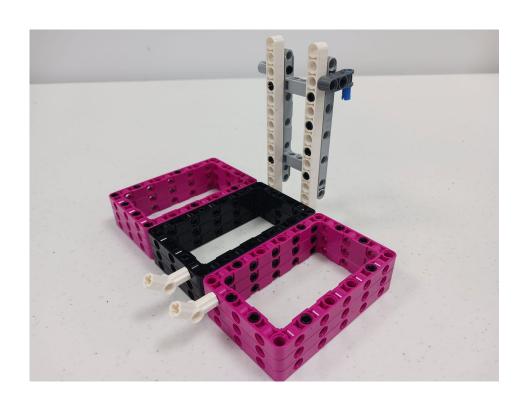


The Energy Dropper
Used to drop energy into the toy factory.



The Windmill Harvester

Used to release and catch energy from the windmill.



The Energy Snagger

For each side of robot to catch energy as it passes.



#### The Hydro Dam Releasers

Used to release the water energy into the other energy unit.



#### The Power Plantanator

Used to release energy from the power plant.

